

certain defination :-

① Kinetic energy of the body is given by

$$T = \frac{1}{2}mv^2$$

② Potential energy of the body is given by the force to displace the body against internal force.

Gravitational potential energy.

$$V = mgh.$$

Elastic Potential energy

$$V = \frac{1}{2}kx^2$$

where $k = \frac{F}{\Delta l}$ = spring constant

③ Pressure energy $E_p = \text{Pressure} \times \text{change in Volume.}$

$$E_p = P \cdot dV.$$

④ Lagrangian function :- The difference of K.E and Potential energy is k/a Lagrangian function 'L'

$$L = T - V$$

⑤ Hamilton function :- The sum of K.E and PE is k/a Hamilton function $H = T + V$

classical Mechanics is divided in to three Groups

- (1) Newtonian Mechanics
- (2) Lagrangian Mechanics
- (3) Hamiltonian Mechanics

Newtonian motion deal the force, displacement acceleration, work, Power, energy of body or system
Lagrangian Mechanics deals the motion of the body with the difference of K.E & P.E

$$L = T - V$$

This chapter is given by me as a definition by you.

Hamiltonian mechanics deals the motion of the particle or system in terms of sum of K.E & P.E

$$H = T + V$$

Newtonian Mechanics

Frame of reference: - The co-ordinate axis attached to the body and observer is K/a frame of reference.

Inertial frame of reference: - The frame of reference which obey the law of inertia is K/a inertial frame of reference.

Hence, body is in uniform motion or at rest has inertial frame of reference.

Let us consider the inertial frame of reference S and S' in which S is at rest and S' is moving with uniform velocity v along x -axis.

The transformation is given by (co-ordinate)

$$x = x' + vt$$

Differentiating it;

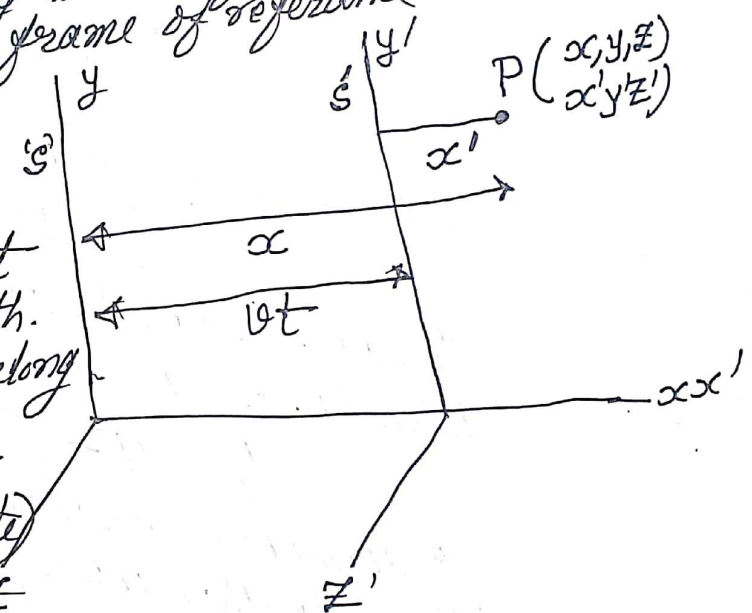
$$\frac{dx}{dt} = \frac{dx'}{dt} + v$$

$$u = u' + v \quad \text{--- (A)}$$

Where u and u' are the velocity of Particle P in S and S' frame respectively.

Differentiating eqn (A) again

$$\frac{du}{dt} = \frac{du'}{dt} + 0 \Rightarrow "a = a'"$$



If $m =$ mass of the Particle P. then

$$ma = ma'$$

or, $F = F'$

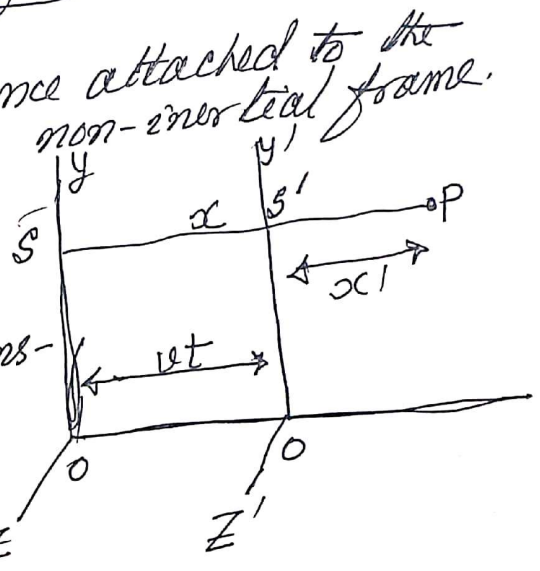
Hence, the force acting upon the particle in both frame are same, Hence, the law of Physics are same in inertial frame.

Non-inertial frame of reference or accelerated frame of reference:-

The frame of reference attached to the accelerated body is k/a non-inertial frame of reference.

Let the body moving with uniform velocity v for the time t . The transformation co-ordinate is given by

$$x = x' + vt$$



Differentiating it we get

$$\frac{dx}{dt} = \frac{dx'}{dt} + v \text{ or, } u = u' + v$$

If the body accelerated after the time t then.

$$\frac{du}{dt} = \frac{du'}{dt} + \frac{dv}{dt}$$

or, $a = a' + a''$

Where a and a' are the acceleration of the body with respect to S and S' . The force acting upon the particle is given by

$$ma = ma' + ma''$$

$$F = F' + F''$$

Hence, in the accelerated frame a vertical force F'' is developed k/a Pseudoforce.